

Complexity of Consistency and Complete State Coding for Signal Transition Graphs

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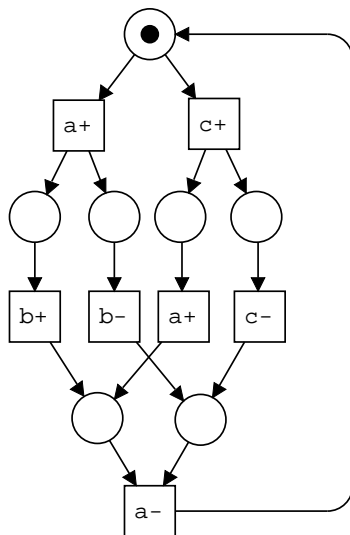
CAK, ES-Colloquium, Prague, 1 February 2007

- A brief recalling of the report from ES-Colloquium 10/2005 on (the following work with colleagues from Univ. Augsburg)
 - Schäfer M., Vogler W., Jančar P.: [Determinate STG Decomposition of Marked Graphs](#); in Proceedings 26th Int. Conf. on [Application and Theory of Petri Nets and Other Models of Concurrency \(ICATPN 2005\)](#), Miami, FL, June 20-25, 2005, [Lecture Notes in Computer Science](#), Vol. 3536, [Springer Verlag](#) 2005, p. 365 - 384
- A more detailed report on (the following work with colleagues from Univ. Stuttgart)
 - Esparza J., Jančar P., Miller A.: [On the Complexity of Consistency and Complete State Coding for Signal Transition Graphs](#); in Proceedings 6th International Conference on [Application of Concurrency to System Design \(ACSD 2006\)](#), Turku, Finland, June 2006, [IEEE Computer Society](#) 2006, pp. 47-56

- Asynchronous circuits.
- Signal transition graphs.
- Consistency problem.
- Complete State Coding (CSC) problem, Unique State Coding (USC) problem.
- Polynomiality of consistency for Marked Graph STGs (MG-STGs).
- Co-NP completeness of CSC and USC problems (for 1-bounded acyclic MG STGs and) for 1-bounded live MG STGs.
- Some additional results.

- For implementation of state dependent circuits
- No clock signal
- Communication with **signal edges** (a^+ raising, a^- falling)
- Distinction between
 - input signals (controlled by the environment)
 - output signals (controlled by the circuit)
- Advantages
 - Average case efficiency instead of worst case efficiency
 - Reduced power consumption
 - Very low electromagnetic emission
- Disadvantage
 - Complex synthesis

A (free-choice) STG



Signal transition graphs - definition

STG: a Petri net based specification of the behaviour of an asynchronous circuit (under some assumptions on the environment).

$A = \{a_1, a_2, \dots, a_n\}$... a set of **signals**

$\mathcal{L} = \{a_1^+, a_1^-, a_2^+, a_2^-, \dots, a_n^+, a_n^-\}$... the set of **(transition) labels**

STG: $S = (N, M_0, \ell)$, where

- (N, M_0) is a Petri net, $N = (P, T, F)$, and
- $\ell : T \longrightarrow \mathcal{L}$

An STG S is **implementable** if there exists a **state coding mapping**

$$\lambda : \text{Reach}(M_0) \longrightarrow \{0, 1\}^n$$

($\lambda(M)$ gives the signal values of the corresponding circuit state)
which is **consistent** and has the **CSC** (or stronger **USC**) **property**.

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Consistency (a characterization)

An STG $S = (N, M_0, \ell)$ is **inconsistent**
(i.e., it admits no consistent state coding mapping)
iff there is

a pair (M, a)
where $M_0 \rightarrow^* M$ and a is a signal

such that one of the following conditions holds:

- (1) M enables ua^+ and va^-
for some a -free sequences u, v ,
- (2) M enables a^+ua^+ or a^-ua^-
for some a -free sequence u ,
- (3) M is reachable by w_1a^+u and by w_2a^-v
for some a -free sequences u, v (and some w_1, w_2).

Complete State Coding (CSC) and Unique SC (USC)

The signal set $A = \{a_1, a_2, \dots, a_n\}$ is partitioned into **input signals** and **output signals**.

A state coding mapping $\lambda : Reach(M_0) \longrightarrow \{0, 1\}^n$ has the **CSC property** if (it is consistent and) it satisfies:

when $\lambda(M) = \lambda(L)$ for two reachable markings $M \neq L$
then M and L enable exactly the same output signals.

λ has the **USC property** if it is injective ($\lambda(M) \neq \lambda(L)$ for $M \neq L$).

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Consistency for Marked Graph STGs (MG STGs)

$S = (N, M_0, \ell)$ is an **MG STG** if

N is a marked graph (net), i.e.,

each place has at most one input and at most one output transition.

We note: (the set of places of) any cycle in an MG is a trap (if marked, it cannot get unmarked) and a siphon (if unmarked, it cannot get marked)

Consistency problem for MG STGs:

Instance: an MG STG $S = (N, M_0, \ell)$

Question: does S admit a consistent state coding mapping ?

We recall:

boundedness, liveness

(any live and bounded MG is strongly connected)

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J. Esparza at ACSD'03:

Consistency is polynomial for **live**, **bounded**, and **cyclic free-choice STGs**

(here 'cyclic' means: the initial marking can always be (re)reached)

(recall that 'free-choice' is the net property guaranteeing that if some output transition of a place is enabled then all its output transitions are enabled)

Remark:

- it is still open if polynomial without cyclicity
- liveness is important: consistency is PSPACE-complete for 1-bounded free choice STGs (as we show here)

Theorem: The consistency is polynomial for (all) MG STGs.

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Ideas for polynomiality of consistency for MG STGs

We call a (N, M_0) normalized if every cycle of N is marked at M_0 .

Claim. Let (N, M_0) be a normalized marked graph, where C_N is the incidence matrix of N .

An integer vector $X_0 \geq 0$ is a solution of the inequation $M_0 + C_N \cdot X \geq 0$ if and only if it is the Parikh vector of a transition sequence σ such that $M_0 \xrightarrow{\sigma}$. (If $M_0 \xrightarrow{\sigma} M$ then $M_0 + C_N \cdot X_0 = M$.)

Claim (a fact from linear programming).

Given C_N where every row contains at most one +1 and at most one -1 (which is the case for MG),

for any linear objective function $f(X)$ the optimal solution X_0 of the inequations $X \geq 0$, $M_0 + C_N \cdot X \geq 0$ (if it exists) is integer, and can be computed in polynomial time (by usual linear programming).

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Ideas for polynomiality of consistency for MG STGs - ctd.

Proposition. A marked graph STG $S = (N, M_0, \ell)$ is inconsistent iff one of the following conditions holds:

(1') there is a reachable M ($M_0 \rightarrow^* M$) such that

$$M \xrightarrow{a^+} \text{ and } M \xrightarrow{a^-} \text{ for some signal } a,$$

(2') there is a reachable M such that

$$M \xrightarrow{a^+ u a^+} \text{ or } M \xrightarrow{a^- u a^-}$$

for some signal a and some a -free sequence u .

The previous claims enable deciding these conditions by using (usual) linear programming.

E.g.: maximize $f(X)$ subject to $X \geq 0$, $M_0 + C_N \cdot X \geq 0$
where

$$f(X) = \sum_{t \in \ell^{-1}(a^+)} X(t) - \sum_{t \in \ell^{-1}(a^-)} X(t)$$

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Co-NP-completeness of USC and CSC for MG STGs

Theorem.

- The CSC problem and the USC problem are co-NP-hard for (1-bounded acyclic marked graph STGs and for) 1-bounded live marked graph STGs.
- The CSC problem and the USC problem for live and bounded free-choice STGs are in co-NP.

We show **the main technical lemma** (of the NP-hardness part); a transition sequence is **balanced** if the numbers of occurrences of labels a^+ and a^- are the same for each signal a :

Lemma. The following problem is **NP-complete**:

Instance: a (consistent) **STG** $S = (N, M_0, \ell)$ such that (N, M_0) is a **1-bounded, acyclic marked graph**.

Question: **is there** an occurrence sequence $M_0 \xrightarrow{\sigma} M_1 \xrightarrow{\tau} M_2$ of S such that τ is **nonempty and balanced** ?

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The crucial point: NP-hardness

Given a boolean formula φ in CNF, we construct a 1-bounded acyclic MG STG S_φ so that

$$\varphi \text{ is satisfiable} \iff S_\varphi \text{ admits } M_0 \xrightarrow{\sigma} M_1 \xrightarrow{\tau} M_2 \\ \text{for some nonempty balanced } \tau.$$

Example. $\varphi \equiv (x_1 \vee \bar{x}_2 \vee x_3) \wedge (x_1 \vee x_2 \vee \bar{x}_3)$

Signals of S_φ :

- x_1, x_2, x_3 (variables)
- c_1, c_2 (clauses)
- $p_{1,1}, p_{1,2}, p_{2,2}, p_{3,1}$ (x_i positively in c_j)
- $n_{2,1}, n_{3,2}$ (x_i negatively in c_j)
- special (auxiliary) signals S_0, S_1, S_2, \dots ('brackets')

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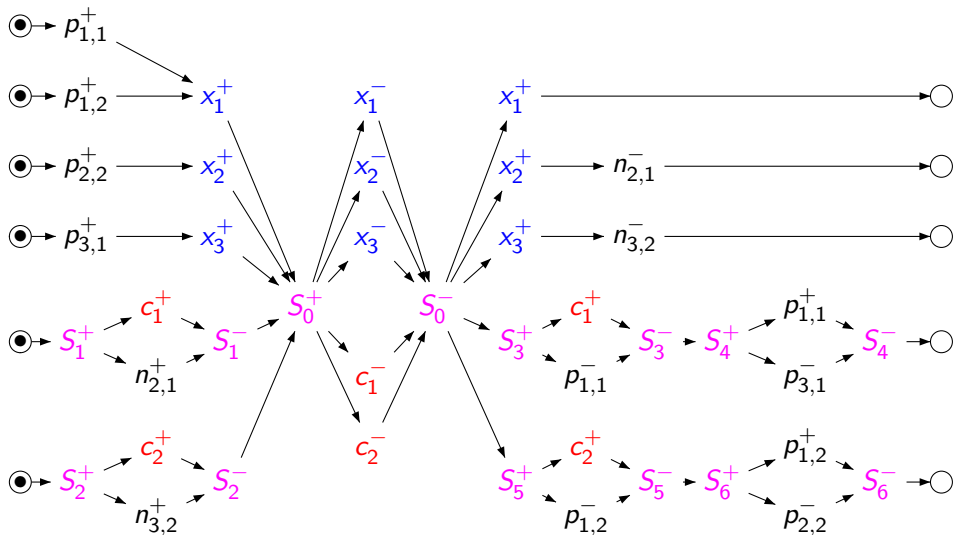
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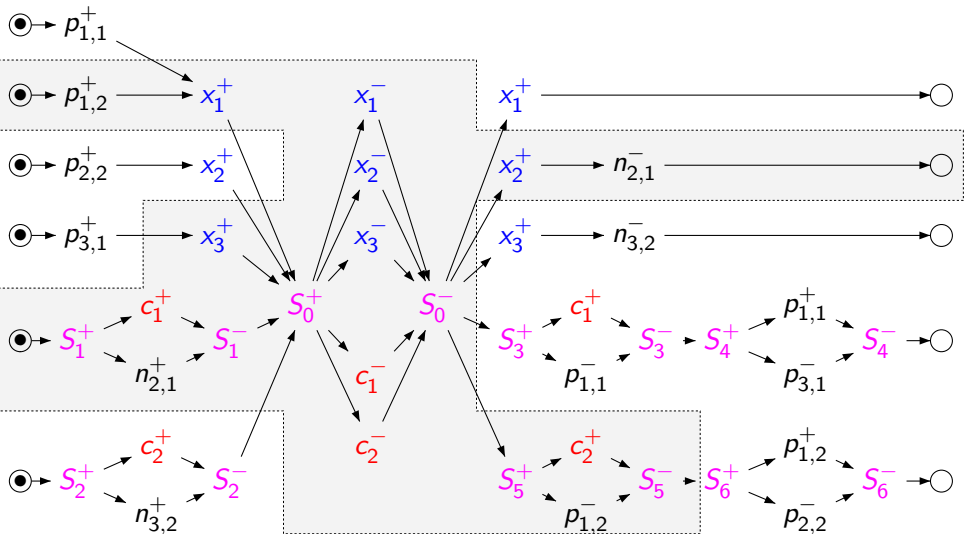
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From 1-bounded acyclic MG to 1-bounded live MG

We define a new STG S'_φ by adding a 'final segment' to S_φ : we add a fresh signal f and construct a 'linear' net N_f with the behaviour

$$f^+ \ell_1 \ell_2 \cdots \ell_k f^-$$

so that S'_φ is a live 1-bounded MG STG and the set of all its transitions is balanced ...

Using of a result by Yamasaki, Huan, Murata (2001):

Theorem.

Let (N, M_0) be a **live and bounded free-choice Petri net**, and let C_N be its incidence matrix.

An integer vector $X_0 \geq 0$ is the Parikh vector of a transition sequence enabled at M_0 **if and only if**

- 1 $M_0 + C_N \cdot X_0 \geq 0$, and
- 2 $M = M_0 + C_N \cdot X_0$ marks all (nonempty) traps of N_{X_0} .

For a net $N = (P, T, F)$ and $X : T \rightarrow \mathbb{N}$, we denote by $N_X = (P_X, T_X, F_X)$ the subnet of N defined as follows: T_X is the set of transitions of T for which $X(t) \geq 1$, $P_X = {}^\bullet T_X \cup T_X^\bullet$, and F_X is the projection of F on $(P_X \times T_X) \cup (T_X \times P_X)$.

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there are sequences u_1, u_2 such that

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- for each signal a :

$$P(u_1)(a^+) - P(u_1)(a^-) = P(u_2)(a^+) - P(u_2)(a^-)$$

- M_1, M_2 enable different output signals

A nondeterministic polynomial algorithm (to check the above condition)

- 1 make several (straightforward) guesses
- 2 create a corresponding system of linear inequalities,
- 3 guess an integer (candidate for) solution of polynomial size,
- 4 check that it is indeed a solution.

(Variables for transition sequences are replaced by variables for their Parikh vectors. The 'trap problem' can be handled by guessing N_X and a subset of its places not containing a trap ...)

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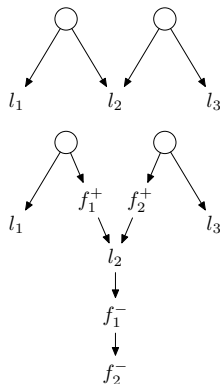
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General bounded STGs

Proposition. The consistency problem, the CSC problem and the USC problem are **PSPACE-complete for k -bounded STGs** (for any fixed k).

Free choice without liveness does not help:

Transforming a 1-bounded STG into a 1-bounded free-choice STG while keeping (in)consistency

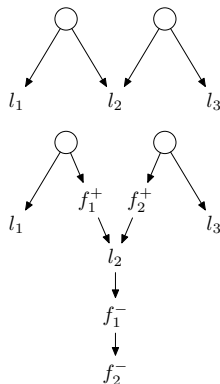


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Proposition. The consistency problem and the CSC problem for general STGs are decidable but EXPSPACE-hard.

(the reachability problem for Petri nets ...)

Some open problems

- Is the CSC (USC) problem polynomial on MG STGs with injective labelling of transitions ?
- Is consistency polynomial for live and bounded free-choice STGs ?